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The perturbation of some exactly soluble problems in wave mechanics by the method of potential envelopes

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Abstract. Suppose the function $\varepsilon_k(v)$ which represents the k th bound-state eigenvalue of the Hamiltonian $\hat{h} = \{-\Delta + v\phi(r) + U(r)\}$ is known exactly for all allowed values of $v \geq 0$. This article concerns the corresponding eigenvalue $E_k(v)$ of the Hamiltonian $H = \{-\Delta + v f(\phi) + U(r)\}$, where $f(\phi)$ is a smooth, increasing, and either convex or concave transformation of the potential $\phi(r)$. An application of the *method of potential envelopes* yields a simple formula for an upper or lower bound to $E_k(v)$ according to whether the transformation $f(\phi)$ is concave or convex. The example $\phi(r) = (-r^{-1} + \omega r)$, $U(r) = \omega^2 r^2$, and $f(\phi) = \lambda^{-1}\{e^{\lambda\phi} - 1\}$ for $\lambda > 0$ is discussed in detail.

1. Introduction

Interesting examples of exactly soluble problems in non-relativistic wave mechanics may be obtained by first choosing the wavefunction and then finding the corresponding potential (Wigner 1929, Reed and Simon 1978, p 223, Killingbeck 1977b, p 985, 1980). Suppose, for example, we consider wavefunctions with the form $\psi(r) = Y_l^m(\theta, \phi)r^l \exp\{-g(r)\}$, $l = 0, 1, 2, \dots$; then Schrödinger's equation

$$(-\Delta + V(r))\psi(r) = \varepsilon\psi(r) \quad (1)$$

becomes

$$(\varepsilon - V(r))r = rg''(r) + 2(l+1)g'(r) - r(g'(r))^2. \quad (2)$$

If we now choose g to have the form $g(r) = \frac{1}{2}(vr + \omega r^2)$, then we can obtain an exact solution of equation (2) by setting

$$V(r) = v\{-(l+1)/r + \omega r\} + \omega^2 r^2 \quad (3)$$

and

$$\varepsilon = (3+2l)\omega - v^2/4. \quad (4)$$

The special cases $l = 0$ and $\omega = 0$ or $v = 0$ correspond respectively to the familiar hydrogen-like and harmonic-oscillator ground-state problems. Unfortunately it is not possible to extend this collection of soluble potentials (say by scaling arguments) to include the potential $V(r) = (-A/r + Br + Cr^2)$ for arbitrary A, B and $C \geq 0$ because the function g which generates the problem has only *two* parameters: if the potential in equation (3) is simply multiplied by a constant, the corresponding exact ground-state

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energy remains unknown. We have recently developed a general approximation theory for *sums* of soluble potentials (Hall 1981) and this can be used to treat those (A, B, C) combinations which have no known exact solutions.

In the present article we use the *method of potential envelopes* (Hall 1980) to show how one can make use of exactly soluble problems such as those arising from equation (2) to approximate the eigenvalues of problems which are 'nearby' in a sense rather different from conventional perturbation theory. In particular we examine potentials of the form

$$V(r) = vf(-r^{-1} + \omega r) + \omega^2 r^2 \quad (5)$$

where f is a smooth increasing function of $\phi = (-r^{-1} + \omega r)$. The principal idea of our geometrical theory is that a *tangent line* to the curve $(\phi, f(\phi))$ has an equation like $y = \alpha + \beta\phi$ with $\beta > 0$ and therefore generates the 'tangential potential' defined by

$$V^{(t)}(r) = v\alpha + v\beta(-r^{-1} + \omega r) + \omega^2 r^2. \quad (6)$$

Consequently, by equations (3) and (4), we know that the Hamiltonian $H^{(t)} = (-\Delta + V^{(t)}(r))$ has the exact lowest eigenvalue given by

$$E^{(t)} = v\alpha + 3\omega - (v\beta)^2/4. \quad (7)$$

The method of potential envelopes which is outlined in §2 prescribes sufficient conditions on f which allow us to relate the unknown eigenvalue E to the tangential eigenvalues $E^{(t)}$. In many cases the method yields a simple algebraic formula, in terms of the functions f and f' , for bounds on E . In §3 we return to the potential $V(r)$ of equation (5) and study the illustration $f(\phi) = (e^{\lambda\phi} - 1)/\lambda$ in some detail.

2. The method of potential envelopes

We suppose that the *exact* eigenvalue $\varepsilon(v)$ corresponding to the lowest bound state of the Hamiltonian

$$\hat{h} = -\Delta + v\phi(r) + U(r) \quad (8)$$

is known for each allowed value of the positive coupling constant v . The graph $(v, \varepsilon(v))$ we call the *energy trajectory* of \hat{h} with respect to ϕ . The new Hamiltonian which we wish to analyse in terms of \hat{h} is given by

$$H = -\Delta + vf(\phi(r)) + U(r) \quad (9)$$

and our aim first of all is to approximate the lowest eigenvalue E of H . We assume that the transformation function f is continuously differentiable and that $f'(\phi) > 0$, for all $\phi(r)$ with $r > 0$.

The key additional assumption which leads to energy *bounds* is that f is either convex or concave: we shall take the case that f is convex for all $\phi(r)$, $r > 0$, which leads to lower energy bounds; upper energy bounds are obtained when f is concave, by an exactly similar argument.

Consider the point $r = s$ and $\phi(s) = t$ which, for the present, we keep constant. We have, by the convexity of f ,

$$f(\phi(r)) \geq f^{(t)}(r) \equiv f(t) + f'(t)\{\phi(r) - t\} \quad \text{all } r > 0. \quad (10)$$

Equation (10) simply states that f lies above the tangent line $f^{(t)}$ which touches f at $\phi = t$.

We call the collection of functions $\{f^{(t)}(r)\}$ an *envelope representation* for the function $g(r) = f(\phi(r))$ and write this $g = \text{Envelope}_{t \in R_\phi} \{f^{(t)}\}$, where R_ϕ is the range of the potential function ϕ .

We can rewrite equation (10) (with t still fixed) in the form

$$f(\phi(r)) \geq f^{(t)}(r) = \alpha(t) + \beta(t)\phi(r) \tag{11}$$

where the ‘constants’ $\alpha(t)$ and $\beta(t)$ are given by

$$\alpha(t) = f(t) - tf'(t) \quad \beta(t) = f'(t) > 0 \text{ (by hypothesis).} \tag{12}$$

We now define the *tangential Hamiltonian* $H^{(t)}$ by

$$H^{(t)} = -\Delta + vf^{(t)}(r) + U(r) \tag{13}$$

and observe that, since $f^{(t)} = \alpha + \beta\phi$, where α and β are *constants*, the exact lowest eigenvalue $E^{(t)}$ of $H^{(t)}$ is given in terms of the known energy-trajectory function $\varepsilon(v)$ of \hat{h} by

$$E^{(t)} = \alpha v + \varepsilon(\beta v). \tag{14}$$

Since $f^{(t)}(r) \leq f(\phi(r))$, $r > 0$, we have, by Weyl’s comparison theorem (e.g. Weinstein and Stenger 1972, p 21), that

$$E^{(t)} \leq E \quad \text{for each fixed choice of } t \in R_\phi \tag{15}$$

where R_ϕ is the range of the function ϕ . The lower bound E^L is now given by

$$E^L = \text{Envelope}_{t \in R_\phi} \{E^{(t)}\} \leq E. \tag{16}$$

Our smoothness assumption concerning f has been made merely for the convenience of using elementary calculus. In the same spirit, we now assume that $f''(t)$ and $\varepsilon'(v)$ are continuous functions so that the envelope in equation (16) can easily be calculated: our assumption that f is convex now becomes $f''(t) > 0$, all $t \in R_\phi$. If we write equation (14) in the form

$$G(v, E, t) = \alpha v + \varepsilon(\beta v) - E = 0 \tag{17}$$

and think of this equation as representing a *family* of curves in the (v, E) plane labelled by the parameter t , then we obtain (e.g. Courant 1936, p 172) the *envelope curve* (v, E^L) of this family by eliminating the parameter t between the two equations

$$G(v, E, t) = 0 \quad \text{and} \quad \frac{\partial G}{\partial t}(v, E, t) = 0. \tag{18}$$

In our problem these envelope equations become explicitly:

$$\begin{aligned} E^L &= v\{f(t) - tf'(t)\} + \varepsilon(vf'(t)) \\ t &= \varepsilon'(vf'(t)). \end{aligned} \tag{19}$$

If equations (19) were difficult to solve, one might prefer to approach the original problem *directly* by using numerical methods. However, in many cases these equations can be rearranged to give E^L and v each as explicit functions of t , that is to say, parametric equations for the graph (v, E^L) . If, for example, $\phi(r)$ is the pure power law $\phi(r) = \text{sgn}(p)r^p$, where p is a constant greater than or equal to -1 , and $U(r) \equiv 0$, then $\varepsilon(v) = \text{sgn}(p)F^{(p)}v^{2/(p+2)}$, where $F^{(p)}$ is a positive constant (Hall 1980), and equations

(19) become in this case (after some algebraic manipulation):

$$\begin{aligned}
 E^L &= \frac{1}{2}v\{2f(t) + ptf'(t)\} & pt > 0 \\
 v &= |2F^{(p)}/t(p+2)|^{(p+2)/p}\{f'(t)\}^{-1}.
 \end{aligned}
 \tag{20}$$

Equations (20) agree, of course, with equation (4.12) of Hall (1980): the actual Hamiltonian for which (v, E^L) provides a lower trajectory bound is given in the notation of the present article by

$$H = -\Delta + vf(\text{sgn}(p)r^p)
 \tag{21}$$

and the equivalence of results is easily verified with the aid of the equations $t = \text{sgn}(p)s^p$ and $ptf'(t) = s df(\text{sgn}(p)s^p)/ds$.

Of course, equations (19) and (20) immediately yield *upper* trajectory bounds when f is *concave*. Also, whenever the trajectory function $\varepsilon_k(v)$ is known for the k th excited state of the base problem \hat{h} , the corresponding energy bound formula yields a bound on the k th eigenvalue E_k of the transformed problem H : this follows because the comparison theorem of Weyl applies to each eigenvalue separately.

3. An example

In order to illustrate the theory of § 2 we need first to choose $\phi(r)$ and $U(r)$ so that the Hamiltonian \hat{h} corresponds to an exactly soluble problem; then we must choose the convex or concave transformation $f(\phi)$ of ϕ which generates the new Hamiltonian H . The present paper is concerned with the class of Hamiltonians discussed in § 1 above where $U(r) = \omega^2 r^2$. We therefore define \hat{h} as follows

$$\begin{aligned}
 \hat{h} &= -\Delta + v\phi(r) + \omega^2 r^2 \\
 \phi(r) &= (-r^{-1} + \omega r) \\
 \varepsilon(v) &= 3\omega - v^2/4
 \end{aligned}
 \tag{22}$$

where $(v, \varepsilon(v))$ is the exact energy trajectory of \hat{h} with respect to ϕ . The Hamiltonian H which we study then becomes

$$H = -\Delta + vf(-r^{-1} + \omega r) + \omega^2 r^2
 \tag{23}$$

where f is increasing and either convex or concave, and will be chosen explicitly later. By applying the theory of § 2 we find the following approximation E^\wedge to the exact energy trajectory $E(v)$ of H (equations (22) have been substituted directly in equations (19) and the resulting equations have been rearranged to give v and E in terms of the parameter t):

$$v = -2t\{f'(t)\}^{-1} \quad E^\wedge = vf(t) + t^2 + 3\omega.
 \tag{24}$$

The parameter t must be in the range of ϕ which, in this example with $\omega \neq 0$, is the entire real line; moreover, since f is assumed to be increasing and v is positive, we see that $t \leq 0$. This means that, in this example, we only make use of that subset of the enveloping family of curves $\{\alpha + \beta\phi(r)\}$ corresponding to points of contact $r = s \leq \omega^{-1/2}$: the rest of the enveloping family gives suboptimal energy estimates.

We now choose the transformation f of ϕ . For the identity $f(\phi) = \phi$, we see from equation (24) that $E^\wedge = \varepsilon(v)$, as we expect. If we choose for f a function which is

convex, then equation (24) will yield a lower trajectory bound which we can compare with an independent variational upper bound. The example we present is

$$f(\phi) = \lambda^{-1}\{e^{\lambda\phi} - 1\} \quad \lambda > 0 \tag{25}$$

which approaches the identity $f(\phi) = \phi$ as $\lambda \downarrow 0$. The actual potential generated in this way (with $\lambda > 0$) has the form

$$V(r) = v\lambda^{-1}\{\exp[\lambda(-r^{-1} + \omega r)] - 1\} + \omega^2 r^2. \tag{26}$$

A sketch of $V(r)$ for the case $v = 2$ and $\omega = 20\lambda = 1$ is shown in figure 1: for $\lambda > 0$, the Coulomb singularity of $\phi(r)$ is removed by the transformation $f(\phi)$ for we have $V(r) \geq \lim_{r \downarrow 0} V(r) = -v\lambda^{-1}$; for large values of r , $V(r) \sim v\lambda^{-1} \exp(\lambda\omega r)$. The (lower) trajectory bound equation (24) becomes (in parametric form)

$$v = 2q e^{\lambda q} \quad q \geq 0 \tag{27a}$$

$$E^L = v\lambda^{-1}\{e^{-\lambda q} - 1\} + q^2 + 3\omega \tag{27b}$$

where we have used the positive parameter $q = -t$. Thus we have in equation (27) a formula for a lower bound to the lowest eigenvalue of the Hamiltonian $H = \{-\Delta + V(r)\}$ which depends on $v \geq 0$, $\omega \geq 0$ and $\lambda > 0$; in the limiting case $\lambda \downarrow 0$, this formula yields of course the exact result $E = 3\omega - v^2/4$. For $\omega = 1$, the graph of $E^L(v)$ for $\lambda = 0.05$ is shown in figure 2 together with a variational upper trajectory bound $E^U(v)$ found by

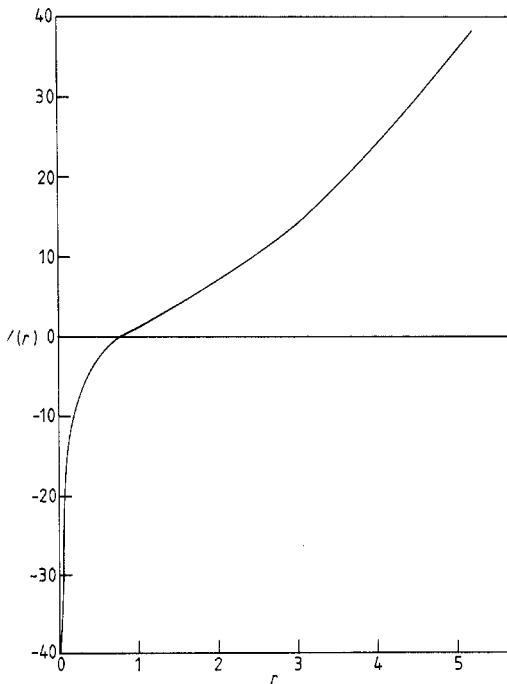


Figure 1. The potential in the example is the smooth transformation $v f(\phi) + \omega^2 r^2$ of the potential $\phi(r) = (-r^{-1} + \omega r)$, in which $f(\phi) = \lambda^{-1}\{\exp(\lambda\phi) - 1\}$. Explicitly we have $V(r) = \omega\lambda^{-1}\{\exp[\lambda(-r^{-1} + \omega r)] - 1\} + \omega^2 r^2$, and the figure illustrates the case $\omega = 20\lambda = 1$, and $v = 2$.

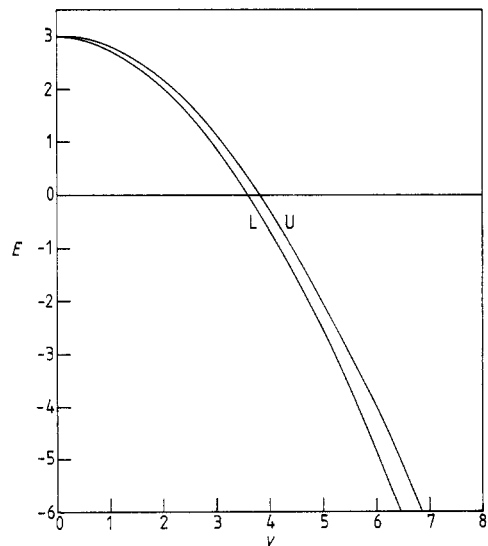


Figure 2. Upper and lower bounds to the lowest eigenvalues $E(v)$ of the Hamiltonian $H = -\Delta + v\lambda^{-1}\{\exp[\lambda(-r^{-1} + \omega r)] - 1\} + \omega^2 r^2$, with $\omega = 1$ and $\lambda = 0.05$: in the limit as $\lambda \downarrow 0$, we have $H = -\Delta + v(-r^{-1} + \omega r) + \omega^2 r^2$ and $E(v) = 3\omega - v^2/4$ exactly.

using the trial function $\psi(r) = \exp\{-ar - br^2\}$ and minimising the expectation of H with respect to the scale variables a and b .

In order to find E^L for a given v numerically, one first solves equation (27a) for q and then substitutes this value of q into (27b). For the case $\omega = 1$, $v = 5$, and $\lambda = 0.01, 0.05$ and 0.1 Killingbeck (1981) has found a numerical approximation E^K to E by the method described in his (1977a) article: these results together with ours are respectively $(E^L, E^K, E^U) = (-3.099, -2.917, -2.908)$, $(-2.578, -1.971, -1.950)$, and $(-2.066, -1.230, -1.160)$.

Of course, our lower bound equation (27) gives the general form of the dependence of E on the triple (v, λ, ω) and this analytical information, which is always interesting, is particularly important for the N -body problem, $N \geq 2$, as we have shown in Hall (1980, 1981). Even for the rather general class of potentials (23), we have a simple recipe (24) which yields lower bounds when $f'' > 0$ and upper bounds when $f'' < 0$.

4. Conclusion

The minimal properties of the eigenvalues of the semi-bounded self-adjoint operators of wave mechanics allow us to use the geometrical ideas of convexity and envelope representations in their study. In this article we submit a component $\phi(r)$ of the potential in the Hamiltonian \hat{h} to a smooth convex or concave transformation $f(\phi)$. This generates a new Hamiltonian H whose k th eigenvalue can be easily approximated provided we know how the k th eigenvalue of \hat{h} depends on the coupling constant v of the component $\phi(r)$, that is to say, the k th energy trajectory of \hat{h} with respect to ϕ . In terms of perturbation theory one can also write

$$H = \hat{h} + v\{f(\phi(r)) - \phi(r)\}. \quad (28)$$

We do not, however, require v to be small: provided f is convex or concave the method always yields a strict energy bound; whenever the curvature of f is small in the region over which the square of wavefunction $|\psi(r)|^2$ is significantly large, the approximation will be good. The purpose of this geometrical theory is to provide a new tool with which to analyse potentials that are near to one of the few potentials we have whose corresponding energy trajectories are known exactly.

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